# Substituent Effects and the In-Plane Distortion of Aromatic Rings: A Group-Theoretical Approach 

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#### Abstract

The distortions of benzene rings caused by substituents are analysed by application of group-theoretical methods. For each substituent there is a vector whose components represent the distortion of individual angles or bonds. Alternatively these vectors can be represented in terms of the symmetry coordinates of a regular hexagon. On the assumption that substituent effects can be linearly combined, formulae are derived for predicting the distortions of polysubstituted benzene derivatives.


## Introduction

In an extensive analysis of the geometry of a large number of selected monosubstituted derivatives of benzene (I) it has been shown (Domenicano, Vaciago \& Coulson, 1975a,b; Domenicano \& Vaciago, 1979) (DVC $a, \mathrm{DVC} b, \mathrm{DV}$ respectively) that substituents on the benzene ring can cause significant in-plane distortions of the carbon skeleton from $D_{6 h}$ symmetry.* These distortions are most significant experimentally when angles rather than bonds are concerned and the largest effect is usually seen at the atom to which the substituent is attached (ipso atom). There is evidence, however, that the angle para to the substituent is also affected and, in general, angular distortions are observed at all six C atoms. Similar distortions are also present in bond lengths but experimental errors are large so that they are not as reliably observed. The quantitative aspects of these distortions are investigated by factor analysis and other methods in a following paper (Domenicano, Murray-Rust \& Vaciago, 1982) (DMRV). In this paper we consider the representation of distortions by vector methods and the combination of distortions caused by polysubstitution in benzene rings.

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In general a substituent (e.g. OMe) may cause different distortions at all six ring angles and all six bonds (Di Rienzo, Domenicano, Portalone \& Vaciago, 1976) but many monatomic or highly symmetrical substituents (e.g. $\mathrm{NO}_{2}, \mathrm{Ph}$, etc.) distort the benzene ring so that it retains $C_{2 v}$ symmetry within experimental error (Fig. 1). In this case there cannot be more than four different angles and three different bonds, but since the ring is planar only five can be independent. (One angle is exactly determined by the other three and there is also a ring-closure condition involving lengths and angles.) In this paper we shall restrict ourselves to substituents where the monosubstituted benzene ring retains $C_{2 v}$ symmetry. It is fairly straightforward to generalize the approach described here to substituents which cause distortions of lower symmetry.

## Combinations of substituent effects

For each symmetrical monosubstituted benzene derivative (I), there is a set of four angular substituent parameters ( $\Delta \alpha, \Delta \beta, \Delta \gamma, \Delta \delta$ ) and three length parameters ( $\Delta a, \Delta b, \Delta c$ ) which are the deviations from a reference unsubstituted benzene molecule with angles of $120^{\circ}$ and $\mathrm{C}-\mathrm{C}$ length $r_{0}$. Elsewhere (Domenicano \& Murray-Rust, 1979) (DMR) we have given a table of the angular parameters for 22 common functional groups. Di- and polysubstituted benzene rings normally have lower symmetry $\left(C_{s}\right)$ and can only be described in terms of these parameters if we assume some method of combining substituent effects. The simplest model is a linear combination and here we shall investigate the geometrical basis of the idea that the distortions caused


Fig. 1. Parameters used to define the geometry of the carbon skeleton in a phenyl derivative retaining $C_{2 v}$ symmetry. H atoms are omitted
by a number of substituents on a benzene nucleus can be represented as the cumulative effect of all the substituents acting independently. Although there is little theoretical justification for this chemically, we have shown (DMR) that for a large number of para-disubstituted benzene derivatives this model gives good agreement with the observed ring angles (bonds were not considered) and gives satisfactory predictions for polysubstituted molecules.* A similar approach has independently been used by Norrestam \& Schepper (1981) in analysing the angular distortion of benzene rings polysubstituted with $\mathrm{Me}, \mathrm{Ph}, \mathrm{Cl}$ and OH .

(I)

## Representation of distortions by symmetry coordinates

The linear combination of distortions of tetrahedra has been fully described both from a group-theoretical aspect and experimentally (Murray-Rust, Bürgi \& Dunitz, 1978a,b) (MBDa,b) and a general procedure, applicable to any point group, has been published (Murray-Rust, Bürgi \& Dunitz, 1979) (MBDc). Much of the notation and nomenclature used here is taken from these papers. Central to the approach is the representation of a distortion as an $n$-dimensional vector $\mathbf{D}$ and its decomposition into $n$ orthogonal components $D_{i}$. Each component is chosen to transform as an irreducible representation (IR) of the point group of the undistorted molecule (reference point group $G$ ). Here we consider a planar irregular hexagon related to the point group $D_{6 h}$. It is shown in many textbooks of applied group theory that there are nine degrees of freedom for an in-plane distortion of a

[^1]regular hexagon and that an arbitrary distortion vector transforms as
\[

$$
\begin{equation*}
A_{1 g}+B_{2 u}+2 E_{2 g}+E_{1 u}+B_{1 u} . \tag{1}
\end{equation*}
$$

\]

The first two relate only to bond-length distortions and the last one only to angle distortions, whereas the degenerate $E$ representations include both bond and angle distortions.

The in-plane distortion of a planar hexagon from a reference structure of $D_{6 h}$ symmetry can be described as a nine-dimensional vector $D$. If we define the deviations from regularity in terms of internal coordinates (Fig. 2) as:

$$
\begin{equation*}
\Delta r_{12}=r_{12}-r_{0}, \text { etc. }, \tag{2}
\end{equation*}
$$

(where $r_{0}$ is the reference bond length of an undistorted hexagon) and

$$
\begin{equation*}
\Delta \theta_{1}=\theta_{1}-120^{\circ}, e t c . \tag{3}
\end{equation*}
$$

the components $\left(D_{i}\right)$ of the distortion vector* can be expressed as linear combinations of $r_{j k}$ and $\theta_{i}$ :

$$
\begin{align*}
& D_{1}\left(A_{1 g}\right)=6^{-1 / 2}\left(\Delta r_{12}+\Delta r_{23}+\Delta r_{34}+\Delta r_{45}\right. \\
&\left.+\Delta r_{56}+\Delta r_{16}\right),  \tag{4}\\
& D_{2}\left(B_{2 u}\right)= 6^{-1 / 2}\left(\Delta r_{12}-\Delta r_{23}+\Delta r_{34}-\Delta r_{45}\right. \\
&\left.+\Delta r_{56}-\Delta r_{16}\right),  \tag{5}\\
& D_{3 a}\left(E_{2 g}\right)= 12^{-1 / 2}\left(-\Delta r_{12}+2 \Delta r_{23}-\Delta r_{34}\right. \\
&\left.\quad-\Delta r_{45}+2 \Delta r_{56}-\Delta r_{16}\right),  \tag{6}\\
& D_{3 b}\left(E_{2 g}\right)=4^{-1 / 2}\left(-\Delta r_{12}+\Delta r_{34}-\Delta r_{45}+\Delta r_{16}\right),  \tag{7}\\
& D_{4 a}\left(E_{2 g}\right)= 12^{-1 / 2}\left(2 \Delta \theta_{1}-\Delta \theta_{2}-\Delta \theta_{3}+2 \Delta \theta_{4}\right. \\
&\left.\quad-\Delta \theta_{5}-\Delta \theta_{6}\right),  \tag{8}\\
& D_{4 b}\left(E_{2 g}\right)= 4^{-1 / 2}\left(\Delta \theta_{2}-\Delta \theta_{3}+\Delta \theta_{5}-\Delta \theta_{6}\right),  \tag{9}\\
& D_{5 a}\left(E_{1 u}\right)= 12^{-1 / 2}\left(2 \Delta \theta_{1}+\Delta \theta_{2}-\Delta \theta_{3}-2 \Delta \theta_{4}\right. \\
&\left.\quad-\Delta \theta_{5}+\Delta \theta_{6}\right),  \tag{10}\\
& D_{5 b}\left(E_{1 u}\right)=4^{-1 / 2}\left(\Delta \theta_{2}+\Delta \theta_{3}-\Delta \theta_{5}-\Delta \theta_{6}\right),  \tag{11}\\
& D_{6}\left(B_{1 u}\right)= 6^{-1 / 2}\left(\Delta \theta_{1}-\Delta \theta_{2}+\Delta \theta_{3}-\Delta \theta_{4}\right. \\
&\left.+\Delta \theta_{5}-\Delta \theta_{6}\right) . \tag{12}
\end{align*}
$$

The form of $D_{1}, D_{2}$ and $D_{6}$ is fixed but there is always a choice of how basis vectors for degenerate representations can be chosen (a problem discussed in detail in MBD $a, c$ ). Here the $E_{2 g}$ distortion has been decomposed into two bond and two angle components and $D_{3 a}$ and $D_{4 a}$ have been chosen so that they correspond to the cokernel symmetry ( $D_{2 h}$ ) of this IR. The

[^2]components $D_{3 b}$ and $D_{4 b}$ correspond only to the lower kernel symmetry, $C_{2 h}$. The $E_{1 u}$ representation contains an inseparable combination of bond and angle components whose relation is essentially the ring-closure condition for hexagons slightly distorted from regularity. Britton (1977) has (without explicitly referring to this IR) derived relationships between bond lengths and angles in planar hexagons. $D_{5 a}$ has the cokernel symmetry ( $C_{2 v}$ ), $D_{s b}$ the kernel symmetry $C_{s}$. The alternative formulations for the $E_{1 u}$ components in terms of bond distortions are:
\[

$$
\begin{align*}
D_{5 a}^{\prime}= & 12^{-1 / 2}\left(2 \Delta r_{23}+\Delta r_{34}-\Delta r_{45}-2 \Delta r_{56}\right. \\
& \left.\quad-\Delta r_{16}+\Delta r_{12}\right)  \tag{13}\\
D_{5 b}^{\prime}= & 4^{-1 / 2}\left(-\Delta r_{34}-\Delta r_{45}+\Delta r_{16}+\Delta r_{12}\right) \tag{14}
\end{align*}
$$
\]

$D_{s a}^{\prime}$ is related to $D_{s b}$ and $D_{s b}^{\prime}$ to $D_{s a}$ by a scale factor derivable from Britton's (1977) equations.

A general nine-dimensional vector $\mathbf{D}$ will contain non-zero components $D_{1}$ to $D_{6}$ and will correspond to a molecule with no symmetry except the $x y$ mirror plane. Distortions where some of the nine components are zero may, however, correspond to (kernel or cokernel) configurations which retain other symmetry elements of $D_{6} h$. Thus a distortion whose vector has all components zero except $D_{2}$ will result in a molecule with $D_{3 h}(x)$ symmetry (the kernel of the $B_{2 u}$ representation). For degenerate representations, symmetries higher than the kernel may occur. Thus if all components except $D_{3 a}$ and $D_{3 b}$ are zero the symmetry of the corresponding molecule will be $C_{2 h}(z)$ (the kernel symmetry of $E_{2 g}$ ) but if only $D_{3 a}$ is non-zero the higher cokernel symmetry $D_{2 h}\left(\sigma_{x z}, \sigma_{y z}\right)$ occurs. The same cokernel symmetry (but preserving other $\sigma_{z}$ planes) can occur in two other circumstances: when $D_{3 a}= \pm 3^{-1 / 2} D_{3 b}$. This situation is concisely expressed in the vector diagram shown in Fig. 3. A bond distortion transforming as $E_{2 g}$ is represented by a vector in this (two-dimensional) diagram, the length of the vector expressing the amount of the distortion. The orientation of the vector relates to the symmetry of the distorted molecule. If the vector happens to lie along any of the six special positions $O A, O B, O C, O \bar{A}, O \bar{B}, O \bar{C}$, the kernel configuration will have the $D_{2 h}$ cokernel symmetry. It can be seen that the symmetry of Fig. 2 is $3 m$ and that $A O \bar{C}$ represents the asymmetric unit. The diagram is noncentrosymmetric so that $O A$ and $O \bar{A}$ represent different distortions. For example, a vector along $O A$ corresponds to a lengthening of the ortho/meta bonds ( $r_{23}$ and $r_{56}$ ) whilst $O \bar{A}$ corresponds to a compression (a quinonoid structure). $O A$ and $O B$ represent isometric distortions identical except for the labelling of the atoms or, alternatively, the orientation of the molecule. For each IR there is a kernel symmetry and for degenerate ones there are also one or more cokernel symmetries (MBDc) and these, along with the sym-


Fig. 3. Representation of bond-length distortions transforming solely as $E_{28}$. The components of a general distortion vector are measured on the orthogonal axes $D_{3 a}$ and $D_{3 b}$. A general vector corresponds to a molecular configuration with the kernel symmetry $C_{2 h}(z)$ but when a vector lies along any of $O A, O \bar{C}$, $O B, O \bar{A}, O C, O \bar{B}$ the molecular configuration has $D_{2 h}$ cokernel symmetry. The numbers in parentheses indicate which of the mirror planes along the $z$ axis is preserved (see Fig. 2). Since distortions $O A$ and $O \bar{A}$ are not equivalent the diagram has $3 m$ symmetry.

Table 1. Kernel and cokernel symmetries for irreducible representations of $D_{6 n}$ where the kernel retains the xy mirror plane (Murray-Rust, Bürgi \& Dunitz, 1979)

Symmetry of deformation space relates to the symmetry of diagrams such as Fig. 3 and Hermann-Mauguin symbols are used (the H groups of MBDc ).

| IR | Kernel | Cokernel(s) | $H$ (symmetry of <br> deformation space) |
| :---: | :--- | :---: | :---: |
| $A_{1 g}$ | $D_{6 h}$ | - | 1 |
| $B_{2 u}$ | $D_{3 h}(x)$ | - | $\overline{1}$ |
| $E_{2 g}$ | $C_{2 h}(z)$ | $D_{2 h}$ | $3 m$ |
| $E_{1 u}$ | $C_{5}(z)$ | $C_{2 v}(x), C_{2 v}(y)$ | $\overline{3} m$ |
| $B_{1 u}$ | $D_{3 h}(y)$ | - | $\overline{1}$ |

metries of the corresponding deformation spaces H , are given in Table 1.

## Substituent parameters for irreducible representations

It will be convenient to consider the distortion caused by a substituent as a nine-dimensional vector having components which transform as individual IR's. Thus a distortion retaining $C_{2 v}$ symmetry (appropriate to a monosubstituted benzene) may have five components $D_{1}, D_{3 a}, D_{4 a}, D_{5 a}, D_{6}$ (see Table 2). No combination of these components can give a non-zero $D_{2}$ component and hence no combination of symmetrical substituents can produce a molecule with $D_{3 h}(x)$ symmetry if our model of linear combination holds.

We shall take the case of a single IR to illustrate the representation of distortion. Assume that at position 1 substituent $X$ causes a bond length distortion ( $\mathbf{X}_{3}$ ) whose $D_{3 a}$ component is $X_{3}$ and whose $D_{3 b}$ component is zero. Assume secondly that all other distortion

Table 2. Subgroups of $D_{6 h}$ which retain the xy mirror plane
For each subgroup are given the distortion coordinates corresponding to IR's with kernel or cokernel symmetries which are supergroups of the group in each row. The combinations marked with an asterisk require the $a$ and $b$ components of a distortion vector to be present in the ratio $1: \pm \sqrt{3}$.

components happen to be zero. Assume also that a different ligand $Y$ at position 1 independently causes a distortion ( $\mathbf{Y}_{3}$ ) whose $D_{3 a}$ component is $Y_{3}$. In general for any symmetrical substituent we assume a scalar substituent parameter for the $E_{2 g}$ (bond) distortion.* Vector diagrams such as Fig. 4 show how substituent effects can be described. The distortion due to each substituent is represented by a vector lying along one of the three axes: $O A$ for substitution at 1 or $4 ; O B$ for substitution at 2 or 5 ; and $O C$ for substitution at 3 or 6 . The magnitude of the vector is the $D_{3}$ substituent effect for each ligand. The case for a monosubstituted benzene ring is shown in Fig. 4(a). The distortion due to $X$ must be combined with the distortions due to the five H atoms and can be seen to result in a final vector along OA of magnitude $\mathbf{X}_{3}-\mathbf{H}_{3}$. It turns out that for all IR's the resultant is always a difference between substituent effects and we shall arbitrarily set all distortion parameters for hydrogen to zero. With this new terminology the hydrogen substituents need not be explicitly considered further.

The $X, Y$ para-disubstitution of benzene is represented in Fig. $5(b)$. The resultant $D_{3}$ vector is simply the

[^3]

Fig. 4. Vector addition of substituent effects in (a) $\bigcirc X$ and
(b) $Y-\bigcirc$ - $X$ for the $E_{28}$ representation (see Fig. 3). Note
that in (b) the substituent effect from hydrogen has been set to zero.

(a)

Fig. 5. Resultant $D_{3}$ distortion vectors (see Fig. 3) for (a)

and (b) are related by a mirror plane and that in (c) the resultant $D_{3}$ is of equal magnitude to $X_{3}$ and lies along $O \bar{C}$, corresponding to $D_{2 h}(36)$ cokernel symmetry.
sum of the individual $X_{3}$ and $Y_{3}$ scalars (either of which may, of course, be negative). Ortho and meta substitution is more involved since the resultant molecule no longer has $D_{2 h}$ cokernel symmetry (Fig. $5 a$ ). It is seen that the resultant vector $O P$ makes an arbitrary angle with $O A$. The corresponding situation for meta substitution is shown in Fig. 5(b). The $D_{3}$ vectors for ortho and meta substitution are identical in magnitude and related by a mirror plane. (This means that if all substituent parameters except $X_{3}$ and $Y_{3}$ happened to be zero, the ortho- and meta-substituted molecules would have the same geometry. Put another way, we expect the $E_{2 g}$ kernel configuration for orthoand meta- $\mathrm{C}_{6} \mathrm{H}_{4} X Y$ to be identical.) Where substituents are identical, distortion vectors may lie in special positions of the deformation space (Fig. 5c). Patterns of polysubstitution are easily worked out in a similar manner.
The $E_{2 g}$ (bond) distortion ( $\mathrm{D}_{3}$ ) has been used as an example but similar combinations of substituent effects are possible for all the other IR's. We have five scalar distortion parameters for a (symmetrical) substituent $X: X_{1}$ (bonds), $X_{3}$ (bonds), $X_{4}$ (angles), $X_{5}$ (angles/bonds) and $X_{6}$ (angles). For the $A_{1 g}$ component the resultant is simply the sum of the substitution parameters regardless of the pattern of ligands:

$$
\begin{equation*}
D_{2}=X_{1}+Y_{1}+Z_{1} \ldots \text { etc. } \tag{15}
\end{equation*}
$$

For $E_{2 g}, E_{1 u}$ and $B_{1 u}$ components, the addition depends on the substitution pattern and this is given in Table 3 for all combinations of up to three ligands and for some special cases of higher substitution. Several points may be noted. Because symmetrical substituents cannot combine to give a non-zero $D_{2}$ component, the total distortion predicted by this model is given by an eight-dimensional vector (whose components are $D_{1}$, $D_{3 a}, D_{3 b}, D_{4 a}, D_{4 b}, D_{5 a}, D_{5 b}, D_{6}$ ). Certain patterns of substitution for certain IR's give a kernel configuration with cokernel symmetry (marked by an asterisk in Table 2). Some types of substitution bear an inverse

Table 3. Linear combination of substituent effects
Substituent effects are expressed as $X_{3}\left(E_{2 g}\right), X_{4}\left(E_{2 g}\right), X_{3}\left(E_{1 u}\right)$ and $X_{6}\left(B_{1 u}\right)$ for a substituent $X$ at position 1. The treatment of $X_{4}$ uses the same equations as $X_{3}$ and is omitted. Additional substituents $Y$ and $Z$ are given similar parameters. The ring is numbered in the same way for all substitution patterns regardless of the position of substituents. Thus $\mathrm{C}(1)$ is always at the right-hand end of the molecule (Fig. 2). By orienting some of the molecules in an unusual manner the relationships are made particularly simple. Entries with asterisks correspond to cokernel configurations for the hexagon (for that particular IR only).

relationship: thus symmetrical para-disubstitution $\left(\mathrm{C}_{6} \mathrm{H}_{4} X_{2}\right)$ should show an exactly opposite distortion (for all IR's and hence for the total distortion vector) to 1,2,4,5-tetrasubstitution ( $\mathrm{C}_{6} \mathrm{H}_{2} \mathrm{X}_{4}$ ). Similar complementarity can be found between other $\mathrm{C}_{6} X_{n} Y_{6-n}$ and $\mathrm{C}_{6} X_{6-n} Y_{n}$ substitution patterns where $X$ and $Y$ are interchanged. More importantly, given the experimental geometry of a molecule we can calculate the components of the distortion and, if some (but not all) of the substituent effects are known, we can calculate other substituent effects by vectorial subtraction. An example of this is given in the Appendix.

## Distortions represented as combinations of internal parameters

We have used symmetry-distortion coordinates to represent distortions because of their geometrical orthogonality, but internal coordinates can also be used. Considering angles alone, the distortion of a monosubstituted benzene $\left(\mathrm{C}_{6} \mathrm{H}_{5} X\right)$ can be described by three components $X_{4}, X_{5}$ and $X_{6}$. For a combination of substituents ( $X, Y \ldots$ ) the angular distortion of a benzene ring is described in general by $D_{4 a}, D_{4 b}, D_{5 a}$, $D_{5 b}$ and $D_{6}$. These can be retransformed into angles with (8)-(12) and the requirement that the sum of $\Delta \theta_{1}$ to $\Delta \theta_{6}$ is zero. Since all these transformations are linear, a linear combination of substituent effects implies a linear combination of individual angle distortions. In many cases this is more useful than the use of symmetry coordinates and elsewhere (DMR) we have shown that angles in para-disubstituted benzene rings are very well represented by linear combinations of the distortions in the appropriate monosubstituted rings.

As an example consider the geometry of (V) as a linear combination of substituent effects. The geometry of the monosubstituted molecules is shown in Fig. 6 The distortions of (II) from regularity can be represented by $\Delta \alpha_{X}, \Delta \beta_{X}, \Delta \gamma_{X}$ and $\Delta \delta_{X}$. Similarly, we use $\Delta \alpha_{Y}$,


Fig. 6. Individual angles in monosubstituted benzene rings, defining substituent effects, and in a trisubstituted ring.
etc. for (III) and $\Delta a_{Z}$, etc. for (IV). The $D_{4 a}$ distortion components for (II), (III) and (IV) (related to the numbering in Fig. 6) are:

$$
\begin{align*}
& D_{4 a}(\mathrm{II})=12^{-1 / 2}\left(2 \Delta \alpha_{X}-2 \Delta \beta_{X}-2 \Delta \gamma_{X}+2 \Delta \delta_{X}\right),(16) \\
& D_{4 a}(\mathrm{III})=12^{-1 / 2}\left(2 \Delta \beta_{Y}-\Delta \gamma_{Y}-\Delta \delta_{Y}+2 \Delta \gamma_{Y}-\Delta \beta_{Y}\right. \\
& \left.\quad-\Delta a_{Y}\right) \\
& =12^{-1 / 2}\left(\Delta \beta_{Y}+\Delta \gamma_{Y}-\Delta \alpha_{Y}-\Delta \delta_{Y}\right),
\end{aligned} \begin{aligned}
& \text { (17)} \begin{array}{l}
D_{4 a}(\mathrm{IV})=12^{-1 / 2}\left(2 \Delta \alpha_{Z}-2 \Delta \beta_{Z}-2 \Delta \gamma_{Z}+2 \Delta \delta_{Z}\right) .(18)
\end{array} \tag{17}
\end{align*}
$$

The linear combination of these distortions results in a $D_{4 a}$ component:

$$
\begin{align*}
D_{4 a}(\mathrm{II}+\mathrm{III}+\mathrm{IV})= & D_{4 a}(\mathrm{II})+D_{4 a}(\mathrm{III})+D_{4 a}(\mathrm{IV}) \\
= & 12^{-1 / 2}\left(2 \Delta \alpha_{X}-2 \Delta \beta_{X}-2 \Delta \gamma_{X}+2 \Delta \delta_{X}\right. \\
& -\Delta a_{Y}+\Delta \beta_{Y}+\Delta \gamma_{Y}-\Delta \delta_{Y}+2 \Delta \alpha_{Z} \\
& \left.-2 \Delta \beta_{Z}-2 \Delta \gamma_{Z}+2 \Delta \delta_{Z}\right) . \tag{19}
\end{align*}
$$

Similar combinations lead to:

$$
\begin{align*}
D_{4 b}(\mathrm{II}+\mathrm{III}+\mathrm{IV})=4^{-1 / 2}\left(-\Delta a_{Y}\right. & +\Delta \beta_{Y} \\
& \left.+\Delta \gamma_{Y}-\Delta \delta_{Y}\right) .  \tag{20}\\
D_{5 a}(\mathrm{II}+\mathrm{III}+\mathrm{IV})= & 12^{-1 / 2}\left(2 \Delta \alpha_{X}+2 \Delta \beta_{X}-2 \Delta \gamma_{X}-2 \Delta \delta_{X}\right. \\
& -\Delta \alpha_{Y}-\Delta \beta_{Y}+\Delta \gamma_{Y}+\Delta \delta_{Y} \\
& \left.-2 \Delta \alpha_{Z}-2 \Delta \beta_{Z}+2 \Delta \gamma_{Z}+2 \Delta \delta_{Z}\right), \tag{21}
\end{align*}
$$

$$
\begin{align*}
& D_{5 b}(\mathrm{II}+\mathrm{III}+\mathrm{IV})=4^{-1 / 2}\left(-\Delta \alpha_{Y}-\Delta \beta_{Y}\right. \\
&\left.+\Delta \gamma_{Y}+\Delta \delta_{Y}\right),  \tag{22}\\
& D_{6}(\mathrm{II}+\mathrm{III}+\mathrm{IV})=6^{-1 / 2}\left(\Delta \alpha_{X}-2 \Delta \beta_{X}+2 \Delta \gamma_{x}-\Delta \delta_{X}\right. \\
&-\Delta \alpha_{Y}+2 \Delta \beta_{Y}-2 \Delta \gamma_{Y}+\Delta \delta_{Y} \\
&\left.-\Delta \alpha_{Z}+2 \Delta \beta_{Z}-2 \Delta \gamma_{Z}+\Delta \delta_{Z}\right) . \tag{23}
\end{align*}
$$

If the angles in (V) are denoted by $\theta_{1}$ to $\theta_{6}$ (Fig. 6) the distortion components will be found to be:

$$
\begin{align*}
& D_{4 a}(\mathrm{~V})=12^{-1 / 2}\left(2 \theta_{1}-\theta_{2}-\theta_{3}+2 \theta_{4}-\theta_{5}-\theta_{6}\right)  \tag{24}\\
& D_{4 b}(\mathrm{~V})=4^{-1 / 2}\left(\theta_{2}-\theta_{3}+\theta_{5}-\theta_{6}\right)  \tag{25}\\
& D_{5 a}(\mathrm{~V})=12^{-1 / 2}\left(2 \theta_{1}+\theta_{2}-\theta_{3}-2 \theta_{4}-\theta_{5}+\theta_{6}\right) \tag{26}
\end{align*}
$$

$$
\begin{align*}
& D_{5 b}(\mathrm{~V})=4^{-1 / 2}\left(\theta_{2}+\theta_{3}-\theta_{5}-\theta_{6}\right),  \tag{27}\\
& D_{6}(\mathrm{~V})=6^{-1 / 2}\left(\theta_{1}-\theta_{2}+\theta_{3}-\theta_{4}+\theta_{5}-\theta_{6}\right) . \tag{28}
\end{align*}
$$

If substituent effects combine linearly we have:

$$
\begin{equation*}
D_{4 a}(\mathrm{~V})=D_{4 a}(\mathrm{II}+\mathrm{III}+\mathrm{IV}), e t c . \tag{29}
\end{equation*}
$$

and combining (19)-(29), we can calculate the angles in (I) as:

$$
\begin{align*}
& \theta_{1}=120+\Delta \alpha_{X}+\Delta \beta_{Y}+\Delta \delta_{Z},  \tag{30}\\
& \theta_{2}=120+\Delta \beta_{X}+\Delta \alpha_{Y}+\Delta \gamma_{Z},  \tag{31}\\
& \theta_{3}=120+\Delta \gamma_{X}+\Delta \beta_{Y}+\Delta \beta_{Z},  \tag{32}\\
& \theta_{4}=120+\Delta \delta_{X}+\Delta \gamma_{Y}+\Delta \alpha_{Z},  \tag{33}\\
& \theta_{5}=120+\Delta \gamma_{X}+\Delta \delta_{Y}+\Delta \beta_{Z},  \tag{34}\\
& \theta_{6}=120+\Delta \beta_{X}+\Delta \gamma_{Y}+\Delta \gamma_{Z} . \tag{35}
\end{align*}
$$

Thus the distortions of $\theta_{1}$ to $\theta_{6}$ from regularity are simply the combination of the respective distortions in (II), (III) and (IV). The quantities $\Delta \alpha_{X}, \Delta \beta_{x}, \Delta \gamma_{X}$ and $\Delta \delta_{X}$ can be regarded as the angular substituent parameters for $X$ but it must be remembered that only three of them can be geometrically independent since $\Delta \alpha_{X}+2 \Delta \beta_{X}+2 \Delta \gamma_{X}+\Delta \delta_{X}=0$.

The combination of angle distortions turned out to be particularly simple because the reference angles were fixed by symmetry. The combination of bond-length distortions is not so simple since we have to include the reference bond length, $r_{0}$, explicitly. Following a similar procedure to that for angles we can derive the expressions for the bond lengths in the trisubstituted molecule ( V ) from a linear combination of the geometries of (II), (III) and (IV):

$$
\begin{align*}
& r_{12}=a_{X}+b_{Y}+c_{Z}-2 r_{0}  \tag{36}\\
& r_{23}=b_{X}+c_{Y}+b_{Z}-2 r_{0}  \tag{37}\\
& r_{34}=c_{X}+c_{Y}+a_{Z}-2 r_{0},  \tag{38}\\
& r_{45}=c_{X}+b_{Y}+a_{Z}-2 r_{0},  \tag{39}\\
& r_{56}=b_{X}+a_{Y}+b_{Z}-2 r_{0},  \tag{40}\\
& r_{16}=a_{X}+a_{Y}+c_{Z}-2 r_{0} . \tag{41}
\end{align*}
$$

Thus, unlike angles, bond-length distortions cannot be combined without a knowledge of the reference bond length, $r_{0}$. This is because the bond lengths transform as a combination of IR's which include the totally symmetric IR. Errors in the experimental determination of $r_{0}$ will be transmitted in double amount to the estimates of $r_{12}$, etc., from (36)-(41). Since there is an apparent bond shortening in many molecules observed by room-temperature X-ray diffraction, symmetrydistortion coordinates may often be more useful.

## Extension to other systems

There is evidence that a similar linear combination of substituent effects holds for other less symmetrical
molecules, such as pyridine (VI). Monosubstitution at the 2,3 , or 4 positions causes distortions but there is no symmetry requirement for them to be equal. Thus for 2 -substitution all six angles may change by different amounts (although there are only five independent angular substituent parameters). The extension to polysubstituted systems is then analogous to (30)-(41). An important difference, however, is that the angles in the reference structure (VI) must now be known since they are not fixed by symmetry.

(VI)

## APPENDIX

We take as an example the trisubstituted molecule in Fig. 7 (Chiaroni, 1971). Considering angles alone (all numbers are in degrees) we can compute:

$$
\begin{aligned}
D_{4 a}= & (2 \times 117.3-119.6-121.7-124.1 \\
& -122.9+2 \times 114.3) / \sqrt{12}=-7.24^{\circ}, \\
D_{4 b}= & (119.6-124.1+122.9-121.7) / 2=-1.65, \\
D_{5 a}= & (2 \times 117.3+119.6-124.1-114.3 \\
& -2 \times 122.9+121.7) / \sqrt{12}=0.72, \\
D_{5 b}= & (119.6+124.1-122.9-121.7) / 2=-0.45, \\
D_{6}= & (117.3-119.6+124.1-114.3 \\
& +122.9-121.7) / \sqrt{6}=3.55 .
\end{aligned}
$$

From Table 3 we find that $D_{4 b}$ and $D_{s b}$ contain only terms related to $Y$ (in this case $\mathrm{NO}_{2}$ ). On the basis of a linear combination of substituent effects we can derive

$$
\begin{aligned}
& D_{4}\left(\mathrm{NO}_{2}\right)=\frac{2 D_{4 b}}{3}=-1.90^{\circ} \\
& D_{5}\left(\mathrm{NO}_{2}\right)=\frac{2 D_{5 b}}{3}=-0.52
\end{aligned}
$$

Fig. 7. The ring angles $\left({ }^{\circ}\right)$ in 3 -nitro- 4 -methyl- $N$-methylaniline (see Appendix).
without having to know the effects of the Me - and MeNH - substituents. (The linear combination is likely to hold well here as there is no mechanism for through-conjugation.) Let us suppose that substituent parameters are known for two of the three parameters. We have published (DMR) values for 22 substituents, among them $\mathrm{NO}_{2}$ and Me , but no values are available for NHMe. They have been estimated as follows on the basis of the linear hypothesis. From DMR we have:

$$
\begin{array}{ll}
\Delta \alpha\left(\mathrm{NO}_{2}\right)=2.9^{\circ} & \Delta \alpha(\mathrm{Me})=-1.9^{\circ} \\
\Delta \beta\left(\mathrm{NO}_{2}\right)=-1.9 & \Delta \beta(\mathrm{Me})=1.0 \\
\Delta \gamma\left(\mathrm{NO}_{2}\right)=0.3 & \Delta \gamma(\mathrm{Me})=0.4 \\
\Delta \delta\left(\mathrm{NO}_{2}\right)=0.4 & \Delta \delta(\mathrm{Me})=-0.7
\end{array}
$$

From (30)-(35) we have

$$
\begin{aligned}
\Delta \alpha(\text { NHMe })+0.3-0.7+120 & =117.3^{\circ} \\
\Delta \beta(\text { NHMe })-1.9+0.4+120 & =119.6 \\
\Delta \gamma(\text { NHMe })+2.9+1.0+120 & =124.1 \\
\Delta \delta(\text { NHMe })-1.9-1.9+120 & =114.3 \\
\Delta \gamma(\text { NHMe })+0.3+1.0+120 & =122.9 \\
\Delta \beta(\text { NHMe })+0.4+0.4+120 & =121.7 .
\end{aligned}
$$

Hence

$$
\begin{aligned}
& \Delta \alpha(\mathrm{NHMe})=-2.3^{\circ} \\
& \Delta \beta(\mathrm{NHMe})=1.0 \\
& \Delta \gamma(\mathrm{NHMe})=0.9 \\
& \Delta \delta(\mathrm{NHMe})=-1.9
\end{aligned}
$$

It is gratifying to note that these values are close to those for $-\mathrm{NH}_{2}$ and $-\mathrm{NMe}_{2}$ (DMR):

$$
\begin{array}{ll}
\Delta \alpha\left(\mathrm{NH}_{2}\right)=-1.3^{\circ} & \Delta \alpha\left(\mathrm{NMe}_{2}\right)=-2.4^{\circ} \\
\Delta \beta\left(\mathrm{NH}_{2}\right)=0.3 & \Delta \beta\left(\mathrm{NMe}_{2}\right)=0.7 \\
\Delta \gamma\left(\mathrm{NH}_{2}\right)=1.0 & \Delta \gamma\left(\mathrm{NMe}_{2}\right)=1.4 \\
\Delta \delta\left(\mathrm{NH}_{2}\right)=-1.3 & \Delta \delta\left(\mathrm{NMe}_{2}\right)=-1.7
\end{array}
$$

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## Structural Studies of Benzene Derivatives.

## XI.* The Structure of $\boldsymbol{p}$-Toluidine Hydrochloride

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#### Abstract

Crystals of the title compound, $\mathrm{C}_{7} \mathrm{H}_{10} \mathrm{~N}^{+} . \mathrm{Cl}^{-}$, are monoclinic, space group $P 2_{1} / c$, with $a=9.116(1), b=$


> * Part X: Colapietro \& Domenicano (1982).

0567-7408/82/112825-05\$01.00
$9.357(1), c=9.913$ (2) $\AA, \beta=108.56(2)^{\circ}, Z=4$.
The structure, originally determined by Von Eller [Bull. Soc. Fr. Minéral. Cristallogr. (1955), 78, 275-300], has been redetermined from 1615 counter intensities and refined to a final $R$ value of 0.0330 . The benzene © 1982 International Union of Crystallography


[^0]:    * Throughout this paper Schoenflies symbols will be used to describe the symmetries of molecular configurations. HermannMauguin symbols are used for the symmetries of the point groups H related to deformation spaces.

[^1]:    * Through-conjugation (i.e. the cooperative effect of a strong $\pi$ donor and a strong $\pi$ acceptor para to each other) is clearly a non-linear effect. Although we have shown that it affects the angles in para-disubstituted molecules, it probably accounts for less than $1 \%$ of the angular variance (DMR).
    

    Fig. 2. Internal parameters describing a planar hexagon. All substituted benzene derivatives discussed in the text will have this orientation and numbering regardless of the position of substituents.

[^2]:    * The numbering of the symmetry coordinates is not the same as in most textbooks, since coordinates involving hydrogen have been omitted.

[^3]:    * For an unsymmetrical substituent, e.g. OMe, a two-dimensional substituent vector will be required, but this case will not be further considered.

